

PART 1 - GENERAL

1.1 SUMMARY

A. Section Includes:

1. DDC system for monitoring and controlling of HVAC systems.

B. Related Requirements:

1. Section 230993.11 "Sequence of Operations for HVAC DDC" for control sequences in DDC systems.
2. Raceways:
 - a. Section 260533 "Raceways and Boxes for Electrical Systems" for raceways for low-voltage control cable.

1.2 DESCRIPTION

- A. General: The control system shall consist of a high-speed, peer-to-peer network of DDC controllers, a control system server, and a web-based operator interface.
- B. System software shall be based on a server/thin-client architecture, designed around the open standards of web technology. The control system server shall be accessed using a Web browser over the control system network, the owner's local area network and (at the owner's discretion) over the Internet. The server shall also act as a "workstation" when running as a server/client platform. Additional clients shall have concurrent access to the "workstation" in this mode.
- C. The intent of the thin-client architecture is to provide operators complete access to the control system via a Web browser. No special software other than a Web browser shall be required to access graphics, point displays, and trends, configure trends, configure points and controllers, or to download programming into the controllers.
- D. System shall use BACnet protocol for communication between the control modules and web server. Communication between the web server and the user's browser shall be HTTP or HTTPS protocol utilizing HTML5. Use of Adobe Flash technology is not acceptable. I/O points, schedules, setpoints, trends, and alarms specified in 23 09 93.11 – "Sequence of Operations for HVAC Controls" shall be BACnet objects.
- E. New DDC system for the Public Works Facility shall fully interface with the Town's existing DDC system.

1.3 APPROVED CONTROL SYSTEMS

2

- A. Manufacturers: Subject to compliance with requirements, provide products by one of the following or an approved equal:
 1. **Distech Controls.**
 2. **Schneider Electric Controls.**
 3. Automated Logic Corporation (ALC), WebCTRL.

4. Johnson Controls Inc.
5. Delta Controls.

1.4 ABBREVIATIONS

- A. The following abbreviations are utilized within this section and the sequences of operations. Refer to mechanical drawings for additional abbreviations.

1. AC: Air Conditioning
2. ACU: Air Conditioning Unit
3. AHU: Air Handling Unit
4. AI: Analog Input
5. AO: Analog Output
6. ATC: Automatic Temperature Control.
7. AUTO: Automatic
8. AUX: Auxiliary
9. AV: Analog Value
10. BAS: Building Automation System.
11. BI: Binary Input
12. BO: Binary Output
13. BV: Binary Value
14. C: Common
15. CFM: Cubic Feet per Minute.
16. CV: Constant Volume
17. DA: Discharge Air
18. DDC: Direct-digital controls.
19. DI: Digital Input.
20. DO: Digital Output.
21. EA: Exhaust Air
22. EF: Exhaust Fan
23. FAS: Fire Alarm System.

- 24. HOA: Hand / Off / Auto
- 25. HVAC: Heating, Ventilating and Air Conditioning.
- 26. HW Hot Water
- 27. HWP Hot Water Pump
- 28. HWR Hot Water Return
- 29. HWS Hot Water Supply
- 30. LAN: Local area network.
- 31. MER: Mechanical Equipment Room.
- 32. NC: Normally Closed
- 33. NO: Normally Open
- 34. OA: Outdoor Air
- 35. PID: Proportional Integral Derivative.
- 36. POT: Portable Operators Terminal.
- 37. RA: Return Air
- 38. RF: Return Fan
- 39. RH: Relative Humidity
- 40. RTU: Roof-top Unit
- 41. SA: Supply Air
- 42. SF: Supply Fan
- 43. SP: Static Pressure
- 44. TEMP: Temperature
- 45. UH: Unit Heater
- 46. VAV: Variable Air Volume
- 47. VFD: Variable Frequency Drive.

1.5 DEFINITIONS

- A. Adjustable (adj.): Adjustable by the end user, through the supplied user interface.
- B. Advanced Application Controllers (AACs): A fully programmable control module. This control module may be capable of some of the advanced features found in Building Controllers

(storing trends, initiating read & write requests, etc.) but it does not serve as a master controller. Advanced Application Controllers may reside on either the Ethernet/IP backbone or on a subnet.

- C. Alarm: The control system shall be configured to generate an alarm when this object exceeds user definable limits, as described in the Sequence of Controls.
- D. Analog Value: An intermediate (software) point that may be editable or read-only. Editable AVs are typically used to allow the user to set a fixed control parameter, such as a setpoint. Read Only AVs are typically used to display the status of a control operation.
- E. Application Specific Controllers (ASCs): A pre-programmed control module which is intended for use in a specific application. ASCs may be configurable, in that the user can chose between various pre-programmed options, but it does not support full custom programming. ASCs are often used on terminal equipment such as VAV boxes or fan coil units. In many vendors' architectures ASCs do not store trends or schedules but instead rely upon a Building Controller to provide those functions.
- F. BACnet Interoperability Building Blocks (BIBB): A BIBB defines a small portion of BACnet functionality that is needed to perform a particular task. BIBBS are combined to build the BACnet functional requirements for a device in a specification.
- G. BACnet/BACnet Standard: BACnet communication requirements as defined by the latest version of ASHRAE/ANSI 135 and approved addenda.
- H. Binary Value: An intermediate (software) point that may be editable or read-only. Editable BVs are typically used to allow the user to set a fixed control parameter, such as a setpoint. Read Only BVs are typically used to display the status of a control operation.
- I. Building Controllers (BCs): A fully programmable control module which is capable of storing trends and schedules, serving as a router to devices on a subnet, and initiating read and write requests to other controllers. Typically this controller is located on the Ethernet/IP backbone of the BAS. In many vendors' architectures a Building Controller will serve as a master controller, storing schedules and trends for controllers on a subnet underneath the Building Controller.
- J. Control Systems Server: A computer(s) that maintain(s) the systems configuration and programming database.
- K. Controller: Intelligent stand-alone control device. Controller is a generic reference to building controllers, custom application controllers, and application specific controllers.
- L. Direct Digital Control: Microprocessor-based control including Analog/Digital conversion and program logic.
- M. Furnished or Provided: The act of supplying a device or piece of equipment as required meeting the scope of work specified and making that device or equipment operational. All costs required to furnish the specified device or equipment and make it operational are borne by the division specified to be responsible for providing the device or equipment.
- N. Gateway: Bi-directional protocol translator connecting control systems that use different communication protocols.

- O. Install or Installed: The physical act of mounting, piping or wiring a device or piece of equipment in accordance with the manufacturer's instructions and the scope of work as specified. All costs required to complete the installation are borne by the division specified to include labor and any ancillary materials.
- P. Integrate: The physical connections from a control system to all specified equipment through an interface as required to allow the specified control and monitoring functions of the equipment to be performed via the control system. Final system shall be integrated with
- Q. Interface: The physical device required to provide integration capabilities from an equipment vendor's product to the control system. The equipment vendor most normally furnishes the interface device. An example of an interface is the chilled water temperature reset interface card provided by the chiller manufacturer in order to allow the control system to integrate the chilled water temperature reset function into the control system.
- R. Local Area Network: Computer or control system communications network limited to local building or campus.
- S. Loop or control loop: Most commonly a PID control loop. Typically a control loop will include a setpoint, an input which is compared to the setpoint, and an output which controls some action based upon the difference between the input and the setpoint. A PID control loop will also include gains for the proportional, integral, and derivative response as well as an interval which controls how frequently the control loop updates its output. These gains may be adjustable by the end user for control loop "tuning," but in self-tuning control loops or loops which have been optimized for a specific application the gains may not be adjustable.
- T. Master-Slave/Token Passing (MS/TP): Data link protocol as defined by the BACnet standard.
- U. Point-to-Point: Serial communication as defined in the BACnet standard.
- V. Primary Controlling LAN: High speed, peer-to-peer controller LAN connecting BCs and optionally AACs and ASCs. Refer to System Architecture below.
- W. Protocol Implementation Conformance Statement (PICS): A written document that identifies the particular options specified by BACnet that are implemented in a device.
- X. Router: A device that connects two or more networks at the network layer.
- Y. Schedule: The control algorithm for this equipment shall include a user editable schedule.
- Z. Trend: The control system shall be configured to collect and display a trend log of this object. The trending interval shall be no less than one sample every 5 minutes. (Change of Value trending, where a sample is taken every time the value changes by more than a user-defined minimum, is an acceptable alternative.)
- AA. Web Services: Web services are a standard method of exchanging data between computer systems using the XML (extensible markup language) and SOAP (simple object access protocol) standards. Web services can be used at any level within a Building Automation System (BAS), but most commonly they are used to transfer data between BAS using different protocols or between a BAS and a non-BAS system such as a tenant billing system or a utility management system.

BB. Wiring: Raceway, fittings, wire, boxes and related items.

1.6 QUALITY ASSURANCE

A. DDC System Manufacturer Qualifications:

1. Nationally recognized manufacturer of DDC systems and products.
2. DDC systems with similar requirements to those indicated for a continuous period of five years within time of bid.
3. Having complete published catalog literature, installation, operation and maintenance manuals for all products intended for use.

B. DDC System Provider Qualifications:

1. Authorized representative of, and trained by, DDC system manufacturer.
2. Demonstrated past experience with installation of DDC system products being installed for period within five consecutive years before time of bid.
3. Demonstrated past experience on five projects of similar complexity, scope and value.
4. Each person assigned to Project shall have demonstrated past experience.

C. Compliance with ANSI/ASHRAE Standard 135, BACnet – A Data Communication Protocol for Building Automation and Control Systems.

1.7 SYSTEM PERFORMANCE

A. Performance Standards. System shall conform to the following minimum standards over network connections. Systems shall be tested using manufacturer's recommended hardware and software for display through the user's web browser.

1. Graphic Display. A graphic with 20 dynamic points shall display with current data within 10 sec.
2. Graphic Refresh. A graphic with 20 dynamic points shall update with current data within 8 sec. and shall automatically refresh every 15 sec.
3. Configuration and Tuning Screens. Screens used for configuring, calibrating, or tuning points, PID loops, and similar control logic shall automatically refresh within 6 sec.
4. Object Command. Devices shall react to command of a binary object within 2 sec. Devices shall begin reacting to command of an analog object within 2 sec.
5. Alarm Response Time. An object that goes into alarm shall be annunciated at the browser within 45 sec.
6. Program Execution Frequency. Custom and standard applications shall be capable of running as often as once every 5 sec.
7. Performance. Programmable controllers shall be able to completely execute DDC PID control loops at a frequency adjustable down to once per sec. Select execution times consistent with the mechanical process under control.

8. Multiple Alarm Annunciation. Each user, connected to network accessing the system through their browser (workstation), shall receive alarms within 5 seconds of one another.

9. Reporting Accuracy. System shall report values with minimum end-to-end accuracy listed in Table 1.

a. Table 1: Reporting Accuracy

- 1) Note 1: Accuracy applies to 10%–100% of scale
- 2) Note 2: For both absolute and differential pressure
- 3) Note 3: Not including utility-supplied meters

MEASURED VARIABLE	REPORTED ACCURACY
SPACE TEMPERATURE	±0.5°C (±1°F)
DUCTED AIR	±0.5°C (±1°F)
OUTSIDE AIR	±1.0°C (±2°F)
DEW POINT	±1.5°C (±3°F)
WATER TEMPERATURE	±0.5°C (±1°F)
DELTA-T	±0.15° (±0.25°F)
RELATIVE HUMIDITY	±5% RH
WATER FLOW	±2% OF FULL SCALE
AIRFLOW (TERMINAL)	±10% OF FULL SCALE (<i>SEE NOTE 1</i>)
AIRFLOW (MEASURING STATIONS)	±5% OF FULL SCALE
AIRFLOW (PRESSURIZED SPACES)	±3% OF FULL SCALE
AIR PRESSURE (DUCTS)	±25 PA (±0.1 IN. W.G.)
AIR PRESSURE (SPACE)	±3 PA (±0.01 IN. W.G.)
WATER PRESSURE	±2% OF FULL SCALE (<i>SEE NOTE 2</i>)
ELECTRICAL (A, V, W, POWER FACTOR)	±1% OF READING (<i>SEE NOTE 3</i>)
CARBON MONOXIDE (CO)	±5% OF READING
CARBON DIOXIDE (CO ₂)	±50 PPM

10. Control Stability and Accuracy. Control loops shall maintain measured variable at setpoint within tolerances listed in Table 2.

a. Table 2: Control Stability and Accuracy

CONTROLLED VARIABLE	CONTROL ACCURACY	RANGE OF MEDIUM
AIR PRESSURE	±50 PA (±0.2 IN. W.G.) ±3 PA (±0.01 IN. W.G.)	0–1.5 KPA (0–6 IN. W.G.) –25 TO 25 PA (–0.1 TO 0.1 IN. W.G.)
AIRFLOW	±10% OF FULL SCALE	
SPACE TEMPERATURE	±1.0°C (±2.0°F)	
DUCT TEMPERATURE	±1.5°C (±3°F)	
HUMIDITY	±5% RH	
FLUID PRESSURE	±10 KPA (±1.5 PSI) ±250 PA (±1.0 IN. W.G.)	MPA (1–150 PSI) 0–12.5 KPA (0–50 IN. W.G.) DIFFERENTIAL

1.8 ACTION SUBMITTALS

A. Product Data: For each type of product include the following:

1. Construction details, material descriptions, dimensions of individual components and profiles, and finishes.
2. Operating characteristics, electrical characteristics, and furnished accessories indicating process operating range, accuracy over range, control signal over range, default control signal with loss of power, calibration data specific to each unique application, electrical power requirements, and limitations of ambient operating environment, including temperature and humidity.
3. Product description with complete technical data, performance curves, and product specification sheets.
4. Installation, operation and maintenance instructions including factors effecting performance.
5. Bill of materials of indicating quantity, manufacturer, and extended model number for each unique product for DDC System Hardware, Central System Hardware and Software, and Controlled Systems.
 - a. Schematic diagrams for all control, communication, and power wiring. Provide a schematic drawing of the central system installation. Label all cables and ports with computer manufacturers' model numbers and functions. Show interface wiring to control system.
 - b. Network riser diagrams of wiring between central control unit and control panels.
 - c. Riser diagrams showing control network layout, communication protocol, and wire types.
 - d. A schematic diagram of each controlled system. The schematics shall have all control points labeled with point names shown or listed. The schematics shall graphically show the location of all control elements in the system.

- e. A schematic wiring diagram of each controlled system. Label control elements and terminals. Where a control element is also shown on control system schematic, use the same name.
- f. A mounting, wiring, and routing plan-view drawing. The design shall take into account HVAC, electrical and other systems' design and elevation requirements. The drawing shall show the specific location of all concrete pads and bases and any special wall bracing for panels to accommodate this work.
- g. A complete description of the operation of the control system, including sequences of operation. The description shall include and reference a schematic diagram of the controlled system.
- h. A point list for each control system. List I/O points and software points specified in Section 23 09 93.11. Indicate alarmed and trended points.

1.9 CLOSEOUT SUBMITTALS

- A. Project Record Documents. Upon completion of installation, submit three copies of record (as-built) documents of the documents shall be submitted for approval prior to final completion and shall include:
 - 1. Project Record Drawings. As-built versions of submittal shop drawings provided as AutoCAD compatible files on suitable solid state media(file format: .DWG, .DXF, .VSD, or comparable) and as 11" x 17" prints.
 - 2. Testing and Commissioning Reports and Checklists. Completed versions of reports, checklists, and trend logs used to meet requirements of Section 23 09 23 Article 3.17 (Control System Demonstration and Acceptance).
 - 3. Operation and Maintenance (O&M) Manual.
 - 4. As-built versions of submittal product data.
 - 5. Names, addresses, and telephone numbers of installing contractors and service representatives for equipment and control systems.
 - 6. Operator's manual with procedures for operating control systems: logging on and off, handling alarms, producing point reports, trending data, overriding computer control, and changing setpoints and variables.
 - 7. Programming manual or set of manuals with description of programming language and syntax, of statements for algorithms and calculations used, of point database creation and modification, of program creation and modification, and of editor use.
 - 8. Engineering, installation, and maintenance manual or set of manuals that explains how to design and install new points, panels, and other hardware; how to perform preventive maintenance and calibration; how to debug hardware problems; and how to repair or replace hardware.
 - 9. Documentation of programs created using custom programming language including setpoints, tuning parameters, and object database. Electronic copies of programs shall

meet this requirement if control logic, setpoints, tuning parameters, and objects can be viewed using furnished programming tools.

10. Graphic files, programs, and database on suitable solid-state media.
11. List of recommended spare parts with part numbers and suppliers.
12. Complete original-issue documentation, installation, and maintenance information for furnished third-party hardware including computer equipment and sensors.
13. Complete original-issue copies of furnished software, including operating systems, custom programming language, operator workstation or web server software, and graphics software.
14. Licenses, guarantees, and warranty documents for equipment and systems.
15. Recommended preventive maintenance procedures for system components, including schedule of tasks such as inspection, cleaning, and calibration; time between tasks; and task descriptions.

1.10 WARRANTY

A. Warrant work as follows:

1. Warrant labor and materials for specified control system free from defects for a period of 12 months after final acceptance. Control system failures during warranty period shall be adjusted, repaired, or replaced at no additional cost or reduction in service to Owner. Respond during normal business hours within 24 hours of Owner's warranty service request.
2. Work shall have a single warranty date, even if Owner receives beneficial use due to early system start-up. If specified work is split into multiple contracts or a multi-phase contract, each contract or phase shall have a separate warranty start date and period.
3. If the engineer determines that equipment and systems operate satisfactorily at the end of final start-up, testing, and commissioning phase, the engineer will certify in writing that control system operation has been tested and accepted in accordance with the terms of this specification. Date of acceptance shall begin warranty period.
4. Provide updates to web server software, project-specific software, graphic software, database software, and firmware that resolve the contractor-identified software deficiencies at no charge during warranty period. If available, Owner can purchase in-warranty service agreement to receive upgrades for functional enhancements associated with above-mentioned items. Do not install updates or upgrades without Owner's written authorization.
5. Exception: Contractor shall not be required to warrant reused devices except those that have been rebuilt or repaired and factory recertified. Installation labor and materials shall be warranted. Demonstrate operable condition of reused devices at time of Engineer's acceptance.

1.11 PRODUCTS NOT FURNISHED OR INSTALLED UNDER BUT INTEGRATED WITH THE WORK OF THIS SECTION

- A. General: The Installer furnishing the DDC network shall meet with the Installer(s) furnishing each of the following products to coordinate details of the interface between these products and the DDC network. The Owner or his designated representative shall be present at this meeting. Each Installer shall provide the Owner and all other Installers with details of the proposed interface including PICS for BACnet equipment, hardware and software identifiers for the interface points, network identifiers, wiring requirements, communication speeds, and required network accessories. The purpose of this meeting shall be to insure there are no unresolved issues regarding the integration of these products into the DDC network. Submittals for these products shall not be approved prior to the completion of this meeting.
- B. Section 23 70 00 Central HVAC Equipment
 - 1. Unit shall be furnished configured to accept control inputs from an external building automation system controller as specified in 23 09 93.11. Factory mounted safeties and other controls shall not interfere with this controller.
- C. Section 23 80 00 – Decentralized HVAC Equipment:
 - 1. Unit ventilators, unit heaters, fan coils, cabinet heaters, convective or fin tube heaters, zone reheat, and similar terminal units: These units shall be furnished configured to accept control inputs from an external building automation system controller as specified in 23 09 03. Factory mounted safeties and other controls shall not interfere with this controller.
- D. Section 23 36 00 - Air terminal unit:
 - 1. VAV boxes: VAV Terminal Units shall be furnished configured to accept control inputs from an external building automation system controller as specified in 23 09 03. Factory mounted safeties and other controls shall not interfere with this controller.
- E. Section 26 29 00 – Low-Voltage Controllers:
 - 1. The variable frequency drive (VFD) vendor shall furnish VFDs with an interface to the control and monitoring points specified in Section 23 09 93.11. These specified points shall be the minimum acceptable interface to the VFD. The connection to these points shall be by one of the following methods:
 - 2. Hardwired connection such as relay, 0-10VDC, or 4-20mA.
 - 3. BACnet/IP network connection.
 - 4. BACnet over ARCNET network connection.
 - 5. BACnet MS/TP network connection.
 - 6. Modbus MS/TP or IP is an acceptable alternative.
 - 7. Communications with Third Party Equipment:

- F. Any additional integral control systems included with the products integrated with the work of this section shall be furnished with a BACnet interface for integration into the Direct Digital Control System described in this specification.

PART 2 - PRODUCTS

2.1 MATERIALS

- A. Use new products the manufacturer is currently manufacturing and selling for use in new installations. Do not use this installation as a product test site unless explicitly approved in writing by Owner. Spare parts shall be available for at least five years after completion of this contract.

2.2 COMMUNICATION

- A. New BAS system shall be fully integrated into City's existing Schneider Electric Control System.**
- B. Control products, communication media, connectors, repeaters, hubs, and routers shall comprise a BACnet internetwork. Controller and operator interface communication shall conform to ANSI/ASHRAE Standard 135, BACnet.
- C. Install new wiring and network devices as required to provide a complete and workable control network.
- D. Use existing Ethernet backbone for network segments marked "existing" on project drawings.
- E. Each controller shall have a communication port for temporary connection to a laptop computer or other operator interface. Connection shall support memory downloads and other commissioning and troubleshooting operations.
- F. Internetwork operator interface and value passing shall be transparent to internetwork architecture.
1. An operator interface connected to a controller shall allow the operator to interface with each internetwork controller as if directly connected. Controller information such as data, status, and control algorithms shall be viewable and editable from each internetwork controller.
 2. Inputs, outputs, and control variables used to integrate control strategies across multiple controllers shall be readable by each controller on the internetwork. Program and test all cross-controller links required to execute control strategies specified in Section 23 09 93.11. An authorized operator shall be able to edit cross-controller links by typing a standard object address or by using a point-and-click interface.
- G. Building Control Panels and Controllers with real-time clocks shall use the BACnet Time Synchronization service. System shall automatically synchronize system clocks daily from an operator-designated device via the internetwork. The system shall automatically adjust for daylight saving and standard time as applicable.

- H. I automatically adjust for daylight saving and standard time as applicable.
- I. System shall be expandable to at least twice the required input and output objects with additional controllers, associated devices, and wiring.
- J. System shall support Web services data exchange with any other system that complies with XML (extensible markup language) and SOAP (simple object access protocol) standards. Web services support shall as a minimum be provided at the workstation or web server level and shall enable data to be read from or written to the system.
 - 1. System shall support Web services read data requests by retrieving requested trend data or point values (I/O hardware points, analog value software points, or binary value software points) from any system controller or from the trend history database.
 - 2. oints) from any system controller or from the trend history database.
 - 3. System shall support Web services write data request to each analog and binary object that can be edited through the system operator interface by downloading a numeric value to the specified object.
 - 4. For read or write requests, the system shall require user name and password authentication and shall support SSL (Secure Socket Layer) or equivalent data encryption.
 - 5. System shall support discovery through a Web services connection or shall provide a tool available through the Operator Interface that will reveal the path/identifier needed to allow a third-party Web services device to read data from or write data to any object in the system which supports this service.
 - 6. Direct access to trend data shall be provided in order to facilitate historical information stored by the system.

2.3 OPERATOR INTERFACE

- A. Operator Interface. The web server shall reside on a high-speed network with the building controllers. Web pages generated by this server shall be compatible with the latest versions of Microsoft Internet Explorer or Edge, Google Chrome, Mozilla Firefox, and Apple Safari browsers. Any of these supported browsers connected to the server shall be able to access all system information. Mobile devices shall be recognized by the web server and shall supply the appropriate system content as needed. The Operator Interface (web server with client devices) shall conform to the BACnet Operator Workstation (B-OWS) or BACnet Advanced Workstation (B-AWS) device profile as specified in ASHRAE/ANSI 135 BACnet Annex L. This includes the ability to configure and/or reconfigure the system from the client device (change programs, graphics, labels, etc.).
- B. Interface (web server with client devices) shall conform to the BACnet Operator Workstation (B-OWS) or BACnet Advanced Workstation (B-AWS) device profile as specified in ASHRAE/ANSI 135 BACnet Annex L. This includes the ability to configure and/or reconfigure the system from the client device (change programs, graphics, labels, etc.).
- C. Communication. Web server and controllers shall communicate using BACnet protocol. Web server and control network backbone shall communicate using ISO 8802-3 (Ethernet) Data

Link/Physical layer protocol and BACnet/IP addressing as specified in ANSI/ASHRAE 135, BACnet Annex J. Communication between the web server and client (workstation) shall be HTTP or HTTPS protocol utilizing HTML5 language. Use of Adobe Flash in any part of the communication infrastructure is not acceptable.

D. Hardware.

1. Web server and/or workstation. Industry-standard hardware shall meet or exceed DDC system manufacturer's recommended specifications and shall meet response times specified elsewhere in this document. The web server may also be configured in client/server fashion to accommodate a "workstation" definition. In "workstation" configuration, the workstation will also perform as a server supplying additional clients as needed. The following hardware requirements apply:
 - a. System storage shall have sufficient memory to accommodate:
 - b. to accommodate:
 - 1) All required system software.
 - 2) A DDC database to accommodate, as a minimum, twice the size of the delivered system database.
 - 3) One year of archival trend data based on the points specified to be trended at their specified trend intervals.
 - c. Provide additional hardware (communication ports, video drivers, network interface cards, cabling, etc.) to facilitate all control functions and software requirements specified for the DDC system.
 - d. Minimum hardware configuration shall include the following:
 - 1) Dual or Quad Core Processor
 - 2) 2- 6 GB RAM
 - 3) 500 GB hard disk providing data at 3.0 Gb/sec (size dependent on historical data storage requirements)
 - 4) 16x DVD+/-RW drive
 - 5) [Operator Workstation Only – Not for Browser Option] Keyboard
 - 6) [Workstation Only] Mouse
 - 7) [Workstation Only] 22-inch 24-bit color monitor with at least 1024 x 768 resolution
 - 8) Serial (USB) and network communication ports, with cables as required for proper DDC system operation

E. System Software.

1. Operating System. Web server shall have an industry-standard professional-grade operating system. Operating system shall meet or exceed the DDC System manufacturer's minimum requirements for their software. Acceptable systems include Microsoft Windows 7, 8 or 10, Microsoft Vista, Windows Server 2008 or 2012, Red Hat Enterprise Linux, or Ubuntu Desktop 12.04.
2. Security. The web server application shall support Transport Layer Security (TLS) with a capability of 256-bit encryption for transmitting private information over the Internet using HTTPS. Additionally, the web server shall have SHA-2 certificate support.
3. Database. System shall support any JDBC (Java Database Connectivity) compliant engine. This includes: MS SQL, My SQL, PostgreSQL and Oracle.
4. System Graphics. The operator interface software shall be graphically based and shall include at least one graphic per piece of equipment or occupied zone, graphics for each chilled water and hot water system, and graphics that summarize conditions on each floor of each building included in this contract. Indicate thermal comfort on floor plan summary graphics using dynamic colors to represent zone temperature relative to zone setpoint.
5. ve to zone setpoint.
 - a. Minimum graphics resolution shall be 1920 x1080 for display of detailed system graphics.
 - b. Functionality. Graphics shall allow operator to monitor system status, to view a summary of the most important data for each controlled zone or piece of equipment, to use point-and-click navigation between zones or equipment, and to edit setpoints and other specified parameters.
 - c. Animation. Graphics shall be able to animate by displaying different image files for changed object status.
 - d. Alarm Indication. Indicate areas or equipment in an alarm condition using color or other visual indicator.
 - e. Format. Graphics shall be saved in an industry-standard format such as BMP, JPEG, PNG, or GIF. Web-based system graphics shall be viewable on browsers compatible with World Wide Web Consortium browser standards. Web graphic format shall require no plug-in) or shall only require widely available no-cost plug-ins (such as Active-X or Adobe Flash).
6. Custom Graphics. Custom graphic files shall be created with the use of a graphics generation package furnished with the system. The graphics generation package shall be a graphically based system to create and modify graphics that are saved in the same formats as are used for system graphics.
7. Graphics Library. Furnish a complete library of standard HVAC equipment graphics such as chillers, boilers, air handlers, terminals, fan coils, and unit ventilators. This library also shall include standard symbols for other equipment including fans, pumps, coils, valves,

pipng, dampers, and ductwork. The library shall be furnished in a file format compatible with the graphics generation package program.

- F. System Applications. System shall provide the following functionality to authorized operators as an integral part of the operator interface or as stand-alone software programs. If furnished as part of the interface, the tool shall be available from each workstation or web browser interface. If furnished as a stand-alone program, software shall be installable on standard IBM-compatible PCs with no limit on the number of copies that can be installed under the system license.
1. Automatic System Database Configuration. Each workstation or web server shall store on its hard disk a copy of the current system database, including controller firmware and software. Stored database shall be automatically updated with each system configuration or controller firmware or software change.
 2. Duration. Each workstation or web server shall store on its hard disk a copy of the current system database, including controller firmware and software. Stored database shall be automatically updated with each system configuration or controller firmware or software change.
 3. Manual Controller Memory Download. Operators shall be able to download memory from the system database to each controller.
 4. System Configuration. The workstation software shall provide a method of configuring the system. This shall allow for future system changes or additions by users under proper password.
 5. On-Line Help. Provide a context-sensitive, on-line help system to assist the operator in operating and editing the system. On-line help shall be available for all applications and shall provide the relevant data for that particular screen. Additional help information shall be available through the use of hypertext.
 6. Video Training. Provide on-line video support to supplement on-line help assistance. Video content shall be relevant and support existing system documentation.
 7. Security. Each operator shall be required to log on to the system with a user name and password in order to view, edit, add, or delete data.
 - a. Operator Access. The user name and password combination shall define accessible viewing, editing, adding, and deleting privileges for that operator. Users with system administrator rights shall be able to create new users and edit the privileges of all existing users. System Administrators shall also be able to vary and deny each operator's privileges based on the geographic location, such as the ability to edit operating parameters in Building A, to view but not edit parameters in Building B, and to not even see equipment in Building C.
 - b. t even see equipment in Building C.
 - c. Password Policy Rules. System administrator shall invoke policies for minimum password strength, including number of characters, special characters and numbers, upper and lower case, etc.

- d. Automatic Log Out. Automatically log out each operator if no keyboard or mouse activity is detected. This auto logoff time shall be user adjustable.
 - e. Encrypted Security Data. Store system security data including operator passwords in an encrypted format. System shall not display operator passwords.
- 8. System Diagnostics. The system shall automatically monitor the operation of all building management panels and controllers. The failure of any device shall be annunciated to the operator
 - 9. Alarm Processing. System input and status objects shall be configurable to alarm on departing from and on returning to normal state. Operator shall be able to enable or disable each alarm and to configure alarm limits, alarm limit differentials, alarm states, and alarm reactions for each system object. Configure and enable alarm points as specified in Section 23 09 93.11 (Sequences of Operation). Alarms shall be BACnet alarm objects and shall use BACnet alarm services.
 - 10. alarm points as specified in Section 23 09 93.11 (Sequences of Operation). Alarms shall be BACnet alarm objects and shall use BACnet alarm services.
 - 11. Alarm Messages. Alarm messages shall use the English language descriptor for the object in alarm in such a way that the operator will be able to recognize the source, location, and nature of the alarm without relying on acronyms or mnemonics.
 - 12. Alarm Reactions. Operator shall be able to configure (by object) what, if any actions are to be taken during an alarm. As a minimum, the workstation or web server shall be able to log, print, start programs, display messages, send e-mail, send SMS text, and audibly annunciate.
 - 13. unciate.
 - 14. Alarm and Event log. Operators shall be able to view all system alarms and changes of state from any location in the system. Events shall be listed chronologically. An operator with the proper security level may acknowledge and delete alarms and archive closed alarms to the workstation or web server hard.
 - 15. Trend Logs. The operator shall be able to configure trend sample or change of value (COV) interval, start time, and stop time for each system data object and shall be able to retrieve data for use in spreadsheets and standard database programs. Controller shall sample and store trend data and shall be able to archive data to the hard disk. Configure trends as specified in Section 23 09 93.11 (Sequences of Operation). Trends shall be BACnet trend objects. As a minimum, all physical points in the system shall be trended within the local controller (AAC, ASC, BC) for at least 277 samples per point. Selected points, as desired, shall be available for historical archiving within the server. The historical archiving capability cannot be less than 2 years.
 - 16. e trended within the local controller (AAC, ASC, BC) for at least 277 samples per point. Selected points, as desired, shall be available for historical archiving within the server. The historical archiving capability cannot be less than 2 years.

17. Object and Property Status and Control. Provide a method for the operator to view, and edit if applicable, the status of any object or property in the system. The status shall be available by menu, on graphics, or through custom programs.
18. Reports and Logs. Operator shall be able to select, to modify, to create, and to print reports and logs. Operator shall be able to store report data in a format accessible by standard spreadsheet and word processing programs.
19. Audit and Security Detail. All users accessing the system shall have their actions recorded. Information recorded shall include: login/logout time and date; system modifications – with before and after values; ability to report user activity based on individual and/or date and time.
20. Standard Reports. Furnish the following standard system reports:
 - a. Objects. System objects and current values filtered by object type, by status (in alarm, locked, normal), by equipment, by geographic location, or by combination of filter criteria.
 - b. Alarm Summary. Current alarms and closed alarms. System shall retain closed alarms for an adjustable period.
 - c. Logs. System shall log the following to a database or text file and shall retain data for an adjustable period:
 - 1) Alarm History.
 - 2) Trend Data. Operator shall be able to select trends to be logged.
21. Environmental Index. System shall monitor all occupied zones and compile an index that provides a numerical indication of the environmental comfort within the zone. As a minimum, this indication shall be based upon the deviation of the zone temperature from the heating or cooling setpoint. If humidity is being measured within the zone then the environmental index shall be adjusted to reflect a lower comfort level for high or low humidity levels. Similarly, if carbon dioxide levels are being measured as an indication of ventilation effectiveness then the environmental index shall be adjusted to indicate degraded comfort at high carbon dioxide levels. Other adjustments may be made to the environmental index based upon additional measurements. The system shall maintain a trend of the environmental index for each zone in the trend log. The system shall also compute an average comfort index for every building included in this contract and maintain trend logs of these building environmental indices. Similarly, the system shall compute the percentage of occupied time that comfortable conditions were maintained within the zones. Through the UI the user shall be able to add a weighting factor to adjust the contribution of each zone to the average index based upon the floor area of the zone, importance of the zone, or other static criteria.
22. ly, the system shall compute the percentage of occupied time that comfortable conditions were maintained within the zones. Through the UI the user shall be able to add a weighting factor to adjust the contribution of each zone to the average index based upon the floor area of the zone, importance of the zone, or other static criteria.

23. Custom Reports. Operator shall be able to create custom reports that retrieve data, including archived trend data, from the system, that analyze data using common algebraic calculations, and that present results in tabular or graphical format. Reports shall be launched from the operator interface.
 24. aic calculations, and that present results in tabular or graphical format. Reports shall be launched from the operator interface.
 25. Time Lapse Graphic Replay. Operator shall be able to “replay” any graphic in the system to see how key values changed over an operator-selected period of time. Operator shall be able to select the starting date/time for this display and the end date/time or the display period. System shall then display the graphic as it would have looked at the beginning of that period, displaying key data, dynamic colors, etc. based upon values recorded at the start time. When the operator starts the replay the graphics and key values shall dynamically change to produce the effect of “fast forwarding” through the designated period of time. Once the system has been operational for at least 30 days, the contractor shall demonstrate that up to 24 hours of data from within the last 30 days can be replayed on any graphic page. Owner’s representative shall choose the graphic pages for this demonstration at the time of the demonstration.
 26. ration at the time of the demonstration.
- G. Workstation Application Editors. Each PC or browser workstation shall support editing of all system applications. The applications shall be downloaded and executed at one or more of the controller panels
1. Controller. Provide a full-screen editor for each type of application that shall allow the operator to view and change the configuration, name, control parameters, and set points for all controllers.
 2. Scheduling. An editor for the scheduling application shall be provided at each workstation. Provide a method of selecting the desired schedule and schedule type. Exception schedules and holidays shall be shown clearly on the calendar. The start and stop times for each object shall be adjustable from this interface.
 3. ace.
 4. Custom Application Programming. Provide the tools to create, edit, debug, and download custom programs. System shall be fully operable while custom programs are edited, compiled, and downloaded. Programming language shall have the following features:
 - a. Language. Language shall be graphically based and shall use function blocks arranged in a logic diagram that clearly shows control logic flow. Function blocks shall directly provide functions listed below, and operators shall be able to create custom or compound function blocks.
 - b. d function blocks.
 - c. Programming Environment. Tool shall provide a full-screen, cursor-and-mouse-driven programming environment that incorporates word processing features such as cut and paste. Operators shall be able to insert, add, modify, and delete custom

programming code, and to copy blocks of code to a file library for reuse in other control programs.

- d. Independent Program Modules. Operator shall be able to develop independently executing program modules that can disable, enable and exchange data with other program modules.
 - e. Debugging and Simulation. Operator shall be able to step through the program observing intermediate values and results. Operator shall be able to adjust input variables to simulate actual operating conditions. Operator shall be able to adjust each step's time increment to observe operation of delays, integrators, and other time-sensitive control logic. Debugger shall provide error messages for syntax and for execution errors.
 - f. e control logic. Debugger shall provide error messages for syntax and for execution errors.
 - g. Conditional Statements. Operator shall be able to program conditional logic using compound Boolean (AND, OR, and NOT) and relational (EQUAL, LESS THAN, GREATER THAN, NOT EQUAL) comparisons.
 - h. Mathematical Functions. Language shall support floating-point addition, subtraction, multiplication, division, and square root operations, as well as absolute value calculation and programmatic selection of minimum and maximum values from a list of values.
 - i. Variables. Operator shall be able to use variable values in program conditional statements and mathematical functions.
 - 1) Time Variables. Operator shall be able to use predefined variables to represent time of day, day of the week, month of the year, and date. Other predefined variables or simple control logic shall provide elapsed time in seconds, minutes, hours, and days. Operator shall be able to start, stop, and reset elapsed time variables using the program language.
- H. System Variables. Operator shall be able to use predefined variables to represent status and results of Controller Software and shall be able to enable, disable, and change setpoints of Controller Software as described in Controller Software section.

2.4 CONTROLLER SOFTWARE

- A. Furnish the following applications for building and energy management. All software applications shall reside and operate in the system controllers. Applications shall be editable through operator workstation, web browser interface, or workstation.
- B. System Security. See Paragraph 2.3.E.5 (Security) and Paragraph 2.3.E.14.c (Operator Activity).
- C. Scheduling. Provide the capability to execute control functions according to a user created or edited schedule. Each schedule shall provide the following schedule options as a minimum:

1. Weekly Schedule. Provide separate schedules for each day of the week. Each schedule shall be able to include up to 5 occupied periods (5 start-stop pairs or 10 events).
 2. Exception Schedules. Provide the ability for the operator to designate any day of the year as an exception schedule. Exception schedules may be defined up to a year in advance. Once an exception schedule has executed, the system shall discard and replace the exception schedule with the standard schedule for that day of the week.
- D. Holiday Schedules. Provide the capability for the operator to define up to 24 special or holiday schedules. These schedules will be repeated each year. The operator shall be able to define the length of each holiday period. System Coordination. Operator shall be able to group related equipment based on function and location and to use these groups for scheduling and other applications.
- E. to define the length of each holiday period. System Coordination. Operator shall be able to group related equipment based on function and location and to use these groups for scheduling and other applications.
- F. Binary Alarms. Each binary object shall have the capability to be configured to alarm based on the operator-specified state. Provide the capability to automatically and manually disable alarming.
- G. Analog Alarms. Each analog object shall have both high and low alarm limits. The operator shall be able to enable or disable these alarms.
- H. Alarm Reporting. The operator shall be able to determine the action to be taken in the event of an alarm. An alarm shall be able to start programs, print, be logged in the event log, generate custom messages, and display on graphics.
- I. Fault Detection Diagnostics (FDD). The system shall provide the ability to follow NIST and ASHRAE standards for enhanced monitoring and alarming. The capability of FDD shall reside in the controller and integral to the programming. Overlay software for primary FDD reporting is not acceptable. FDD capabilities shall include diagnostics for: Simultaneous Heating and Cooling; Continuous Operation; Fraction of Outdoor Air; Analog Output Cycling; Discrete Output Cycling; Sensor Failures; and Run Requests Analytics. Equipment using these FDD capabilities, as a minimum, shall include: Single Zone Units (SZU), VAV Air Handlers, VAV Terminal Units, Fan Coils, Air Source Heat Pumps.
- J. Remote Communication. System shall automatically contact operator workstation or server on receipt of critical alarms. If no network connection is available, system shall use a modem connection.
- K. Maintenance Management. The system shall be capable of generating maintenance alarms when equipment exceeds adjustable runtime, equipment starts, or performance limits. Configure and enable maintenance alarms as specified in 23 09 93.11 (Sequences of Operation).
- L. PID Control. System shall provide direct- and reverse-acting PID (proportional-integral-derivative) algorithms. Each algorithm shall have anti-windup and selectable controlled variable, setpoint, and PID gains. Each algorithm shall calculate a time-varying analog value that can be used to position an output or to stage a series of outputs. The calculation interval,

PID gains, and other tuning parameters shall be adjustable by a user with the correct security level.

- M. Staggered Start. System shall stagger controlled equipment restart after power outage. Operator shall be able to adjust equipment restart order and time delay between equipment restarts.
- N. rolled equipment restart after power outage. Operator shall be able to adjust equipment restart order and time delay between equipment restarts.
- O. Anti-Short Cycling. All binary output objects shall be protected from short cycling by means of adjustable minimum on-time and off-time settings.
- P. On and Off Control with Differential. Provide an algorithm that allows a binary output to be cycled based on a controlled variable and a setpoint. The algorithm shall be direct-acting or reverse-acting.
- Q. Runtime Totalization. Provide software to totalize runtime for each binary input and output. Operator shall be able to enable runtime alarm based on exceeded adjustable runtime limit. Configure and enable runtime totalization and alarms as specified in Section 23 09 93.11 (Sequence of Operations).

2.5 CONTROLLERS

- A. General. Provide an adequate number of Building Controllers (BC), Advanced Application Controllers (AAC), Application Specific Controllers (ASC), Smart Actuators (SA), and Smart Sensors (SS) as required to achieve performance specified in Section 23 09 23 Article 1.9 (System Performance). Every device in the system which executes control logic and directly controls HVAC equipment must conform to a standard BACnet Device profile as specified in ANSI/ASHRAE 135, BACnet Annex L. Unless otherwise specified, hardwired actuators and sensors may be used in lieu of BACnet Smart Actuators and Smart Sensors
- B. ardwired actuators and sensors may be used in lieu of BACnet Smart Actuators and Smart Sensors
- C. BACnet.
 - 1. Building Controllers (BCs): Each BC shall conform to BACnet Building Controller (B-BC) device profile as specified in ANSI/ASHRAE 135, BACnet Annex L, and shall be listed as a certified B-BC in the BACnet Testing Laboratories (BTL) Product Listing.
 - 2. Advanced Application Controllers (AACs): Each AAC shall conform to BACnet Advanced Application Controller (B-AAC) device profile as specified in ANSI/ASHRAE 135, BACnet Annex L and shall be listed as a certified B-AAC in the BACnet Testing Laboratories (BTL) Product Listing.
 - 3. Application Specific Controllers (ASCs): Each ASC shall conform to BACnet Application Specific Controller (B-ASC) device profile as specified in ANSI/ASHRAE 135, BACnet Annex L and shall be listed as a certified B-ASC in the BACnet Testing Laboratories (BTL) Product Listing.
 - 4. Smart Actuators (SAs): An actuator which is controlled by a network connection rather than a binary or analog signal (0-10v, 4-20mA, relay, etc.). Each SA shall conform to

BACnet Smart Actuator (B-SA) device profile as specified in ANSI/ASHRAE 135, BACnet Annex L and shall be listed as a certified B-SA in the BACnet Testing Laboratories (BTL) Product Listing.

5. Smart Sensors (SSs): A sensor which provides information to the BAS via network connection rather than a binary or analog signal (0-10000 ohm, 4-20mA, dry contact, etc.). Each SS shall conform to BACnet Smart Sensor (B-SS) device profile as specified in ANSI/ASHRAE 135, BACnet Annex L and shall be listed as a certified B-SS in the BACnet Testing Laboratories (BTL) Product Listing.
6. BACnet Communication.
 - a. Each BC shall reside on or be connected to a BACnet network using ISO 8802-3 (Ethernet) Data Link/Physical layer protocol and BACnet/IP addressing.
 - b. BACnet routing shall be performed by BCs or other BACnet device routers as necessary to connect BCs to networks of AACs and ASCs.
 - c. Each AAC shall reside on a BACnet network using ISO 8802-3 (Ethernet) Data Link/Physical layer protocol with BACnet/IP addressing, or it shall reside on a BACnet network using the ARCNET or MS/TP Data Link/Physical layer protocol.
 - d. Each ASC shall reside on a BACnet network using the ARCNET or MS/TP Data Link/Physical layer protocol.
 - e. Each SA shall reside on a BACnet network using the ARCNET or MS/TP Data Link/Physical layer protocol.
 - f. Each SS shall reside on a BACnet network using ISO 8802-3 (Ethernet) Data Link/Physical layer protocol with BACnet/IP addressing, or it shall reside on a BACnet network using ARCNET or MS/TP Data Link/Physical layer protocol.

D. Security.

1. Provide BACnet firewall capability, as defined in the BACnet standard, for controllers that are IP capable.

E. Communication.

1. Service Port. Each controller shall provide a service communication port for connection to a Portable Operator's Terminal. Connection shall be extended to space temperature sensor ports where shown on drawings.
2. Signal Management. BC and ASC operating systems shall manage input and output communication signals to allow distributed controllers to share real and virtual object information and to allow for central monitoring and alarms.
3. Data Sharing. Each BC and AAC shall share data as required with each networked BC and AAC.
4. Stand-Alone Operation. Each piece of equipment specified in Section 23 09 93.11 shall be controlled by a single controller to provide stand-alone control in the event of

communication failure. All I/O points specified for a piece of equipment shall be integral to its controller. Provide stable and reliable stand-alone control using default values or other method for values normally read over the network such as outdoor air conditions, supply air or water temperature coming from source equipment, etc.

5. r air conditions, supply air or water temperature coming from source equipment, etc.
- F. Environment. Controller hardware shall be suitable for anticipated ambient conditions.
1. Controllers used outdoors or in wet ambient conditions shall be mounted in waterproof enclosures and shall be rated for operation at 20°F to 140°F.
 2. Controllers used in conditioned space shall be mounted in dust-protective enclosures and shall be rated for operation at 0°C to 50°C (32°F to 120°F).
- G. Local graphical keypad and display (where applicable). Provide a local graphical keypad and display for each BC and AAC. Operator shall be able to use keypad to view and edit data. The local interface shall be customizable with graphics particular the equipment and function. Real-Time Clock. Controllers that perform scheduling shall have a real-time clock.
- H. Serviceability. Provide diagnostic LEDs for power, communication, and processor. All wiring connections shall be made to a field-removable modular terminal strip or to a termination card connected by a ribbon cable. Each BC and AAC shall continually check its processor and memory circuit status and shall generate an alarm on abnormal operation. System shall continuously check controller network and generate alarm for each controller that fails to respond.
- I. o a termination card connected by a ribbon cable. Each BC and AAC shall continually check its processor and memory circuit status and shall generate an alarm on abnormal operation. System shall continuously check controller network and generate alarm for each controller that fails to respond.
- J. Memory.
1. Controller memory shall support operating system, database, and programming requirements.
 2. Each BC and AAC shall retain BIOS and application programming for at least 72 hours in the event of power loss.
 3. Each ASC and SA shall use nonvolatile memory and shall retain BIOS and application programming in the event of power loss. System shall automatically download dynamic control parameters following power loss.
- K. Immunity to Power and Noise. Controllers shall be able to operate at 90% to 110% of nominal voltage rating and shall perform an orderly shutdown below 80% nominal voltage. Operation shall be protected against electrical noise of 5 to 120 Hz and from keyed radios up to 5 W at 1 m (3 ft).
- L. Transformer. ASC power supply shall be fused or current limiting and shall be rated at a minimum of 125% of ASC power consumption.

2.6 INPUT AND OUTPUT INTERFACE

- A. General. Hard-wire input and output points to BCs, AACs, ASCs, or SAs.
- B. Protection. All input points and output points shall be protected such that shorting of the point to itself, to another point, or to ground shall cause no damage to the controller. All input and output points shall be protected from voltage up to 24 V of any duration, such that contact with this voltage will cause no controller damage.
- C. Binary Inputs. Binary inputs shall allow the monitoring of ON/OFF signals from remote devices. The binary inputs shall provide a wetting current of at least 12 mA to be compatible with commonly available control devices and shall be protected against contact bounce and noise. Binary inputs shall sense dry contact closure without application of power external to the controller.
- D. Pulse Accumulation Inputs. Pulse accumulation inputs shall conform to binary input requirements and shall also accumulate up to 10 pulses per second.
- E. pulses per second.
- F. Analog Inputs. Analog inputs shall monitor low-voltage (0–10 Vdc), current (4–20 mA), or resistance (thermistor or RTD) signals. Analog inputs shall be compatible with and field configurable to commonly available sensing devices.
- G. Binary Outputs. Binary outputs shall provide for ON/OFF operation or a pulsed low-voltage signal for pulse width modulation control. Binary outputs on. Building Controllers have three-position (on-off-auto) override switches and status lights. Outputs shall be selectable for normally open or normally closed operation.
- H. Analog Outputs. Analog outputs shall provide a modulating signal for the control of end devices. Outputs shall provide either a 0–10 Vdc or a 4–20 mA signal as required to properly control output devices. Each Building Controller analog output shall have a two-position (auto-manual) switch, a manually adjustable potentiometer, and status lights. Analog outputs shall not drift more than 0.4% of range annually.
- I. Tri-State Outputs. Control three-point floating electronic actuators without feedback with tri-state outputs (two coordinated binary outputs). Tri-State outputs may be used to provide analog output control in zone control and terminal unit control applications such as VAV terminal units, duct-mounted heating coils, and zone dampers.
- J. uct-mounted heating coils, and zone dampers.
- K. Universal Inputs and Outputs. Inputs and outputs that can be designated as either binary or analog in software shall conform to the provisions of this section that are appropriate for their designated use.
- L. System Object Capacity. The system size shall be expandable to at least twice the number of input/ output objects required for this project. Additional controllers (along with associated devices and wiring) shall be all that is necessary to achieve this capacity requirement. The operator interfaces installed for this project shall not require any hardware additions or software revisions in order to expand the system

2.7 POWER SUPPLIES AND LINE FILTERING

- A. Power Supplies. Control transformers shall be UL listed. Furnish Class 2 current-limiting type or furnish over-current protection in primary and secondary circuits for Class 2 service in accordance with NEC requirements. Limit connected loads to 80% of rated capacity.
1. DC power supply output shall match output current and voltage requirements. Unit shall be full-wave rectifier type with output ripple of 5.0 mV maximum peak-to-peak. Regulation shall be 1.0% line and load combined, with 100-microsecond response time for 50% load changes. Unit shall have built-in over-voltage and over-current protection and shall be able to withstand 150% current overload for at least three seconds without trip-out or failure.
 - a. Unit shall operate between 0°C and 50°C (32°F and 120°F). EM/RF shall meet FCC Class B and VDE 0871 for Class B and MILSTD 810C for shock and vibration.
 - b. shall meet FCC Class B and VDE 0871 for Class B and MILSTD 810C for shock and vibration.
 - c. Line voltage units shall be UL recognized and CSA listed.
- B. Power Line Filtering.
1. Provide internal or external transient voltage and surge suppression for workstations and controllers. Surge protection shall have:
 - a. Dielectric strength of 1000 V minimum
 - b. Response time of 10 nanoseconds or less
 - c. Transverse mode noise attenuation of 65 dB or greater
 - d. Common mode noise attenuation of 150 dB or greater at 40–100 Hz

2.8 AUXILIARY CONTROL DEVICES

- A. Automatic control dampers: low leakage airfoil blade types.
1. Manufacturers: Subject to compliance with requirements, provide products by one of the following or an approved equal:
 - a. Ruskin.
 - b. Tamco.
 2. Construction:
 - a. Frames: Extruded aluminum hat channel, 0.125" minimum thickness.
 - b. Blades: Extruded aluminum airfoil type, 6" maximum blade width.
 - c. Hardware: Molded synthetic bearings. Zinc plated steel axles, linkage brackets, connecting rods, and mounting bolts.

- d. Seals: Flexible metal compression seals on frame at blade end; extruded vinyl inflatable blade edge seals.
 3. Leakage: Not more than 6 CFM per square foot damper area at differential pressure of 4 inches with applied torque at damper of 50 inch-pounds.
 4. Operating Limits:
 5. Temperature:-20 to 200 F
Pressure: 6 inches WG differential
Velocity: Up to 4000 FPM
 6. Select opposed blade dampers for proportional service. Parallel blade dampers may be used for two-position service, or in mixed air application which promotes air mixing.
 7. Damper sizes shall be provided as indicated or defined in specifications. Damper sizes may be provided different from those indicated on the drawings if improved performance can be demonstrated with calculations.
 8. Dampers at exterior walls shall be Tamco 9000 or approved equal.
- B. Electric Damper and Valve Actuators.
1. Stall Protection. Mechanical or electronic stall protection shall prevent actuator damage throughout the actuator's rotation.
 2. Spring-return Mechanism. Actuators used for power-failure and safety applications shall have an internal mechanical spring-return mechanism or an uninterruptible power supply (UPS).
 3. Signal and Range. Proportional actuators shall accept a 0–10 Vdc or a 0–20 mA control signal and shall have a 2–10 Vdc or 4–20 mA operating range. (Floating motor actuators may be substituted for proportional actuators in terminal unit applications as described in paragraph 2.6H.)
 4. Wiring. 24 Vac and 24 Vdc actuators shall operate on Class 2 wiring.
 5. Manual Positioning. Operators shall be able to manually position each actuator when the actuator is not powered. Non-spring-return actuators shall have an external manual gear release. Spring-return actuators with more than 7 N·m (60 in.-lb) torque capacity shall have a manual crank.
- C. Temperature Sensors.
1. Type. Temperature sensors shall be thermistor (10k Type2).
 2. Duct Sensors. Duct sensors shall be single point or averaging as shown. Averaging sensors shall be a minimum of 1.5 m (5 ft) in length per 1 m² · (10 ft²) of duct cross-section.
 3. Immersion Sensors. Provide immersion sensors with a separable stainless steel well. Well pressure rating shall be consistent with system pressure it will be immersed in. Well shall withstand pipe design flow velocities.

4. Space Sensors. Space sensors shall have setpoint adjustment, override switch, display, and communication port as shown.
5. Differential Sensors. Provide matched sensors for differential temperature measurement.

D. Humidity Sensors.

1. Duct and room sensors shall have a sensing range of 20%–80%.
2. Duct sensors shall have a sampling chamber.
3. Outdoor air humidity sensors shall have a sensing range of 20%–95% RH and shall be suitable for ambient conditions of 40°F–170°F.
4. Humidity sensors shall not drift more than 1% of full scale annually.

E. Relays.

1. Control Relays. Control relays shall be plug-in type, UL listed, and shall have dust cover and LED “energized” indicator. Contact rating, configuration, and coil voltage shall be suitable for application.
2. Time Delay Relays. Time delay relays shall be solid-state plug-in type, UL listed, and shall have adjustable time delay. Delay shall be adjustable $\pm 100\%$ from setpoint shown. Contact rating, configuration, and coil voltage shall be suitable for application. Provide NEMA 1 enclosure for relays not installed in local control panel.
3. in local control panel.

F. HOA (Hand-Off-Auto) Relay with Current Switch:

1. Provide for equipment with ECM motors, including but not limited to exhaust fans.
2. Manufacturers: Subject to compliance with requirement, provide products by one of the following:
 - a. Veris Hawkeye H540
 - b. Functional Devices
 - c. Substitutions are permitted.
3. Provide with indicating nameplates. Manual operation, 3 position type with SPDT contacts or DPDT as required for the application and rated for application.
4. HOA with current switch (HOA) shall be used for monitoring motor operation and motor control. Switch shall be adjustable so that a contact closure is made any time the motor is operating within a “normal” range (0.25-15 amps). Low motor amps resulting from low loading or belt failure shall indicate “OFF”. HOA shall be equipped with an onboard command relay and Hand-Off-Auto Switch for motor starter start/stop control. Induced current from the motor shall power the HOA. The HOA shall provide visual indication (LED’s) for output status and sensor power; shall have an adjustable trip setpoint to $\pm 1\%$ of its range from -15 to 60 degrees C; shall be isolated to 600 VAC rms; shall have an adjustable mounting bracket for installation flexibility. Output shall be N.O., Solid State, 1 A @ 30 VAC/DC.

G. POSITION LIMIT SWITCHES

1. Manufacturers: Subject to compliance with requirements, available manufacturers offering products that may be incorporated into the Work include, but are not limited to the following:
 - a. Allen-Bradley.
 - b. AROMAT/NAIS.
 - c. Cutler-Hammer.
 - d. Square D.
2. Description: Momentary type, adjustable limit switch for monitoring motion of damper at a prescribed arc of rotation. Switch shall have oil tight contacts that operate by way of trip lever. Switch shall have DPDT contact arrangement that exceeds load requirements for voltage and current. Submit installation detail on how trip lever mechanism will be actuated for approval prior to installation. The use of ball bearings or mercury is unacceptable.

H. Override Timers.

1. Unless implemented in control software, override timers shall be spring-wound line voltage, UL Listed, with contact rating and configuration required by application. Provide 0–6 hour calibrated dial unless otherwise specified. Flush mount timer on local control panel face or where shown.

I. Current Transmitters.

1. AC current transmitters shall be self-powered, combination split-core current transformer type with built-in rectifier and high-gain servo amplifier with 4–20 mA two-wire output. Full-scale unit ranges shall be 10 A, 20 A, 50 A, 100 A, 150 A, and 200 A, with internal zero and span adjustment. Unit accuracy shall be $\pm 1\%$ full-scale at 500 ohm maximum burden.
2. Transmitter shall meet or exceed ANSI/ISA S50.1 requirements and shall be UL/CSA recognized.
3. Unit shall be split-core type for clamp-on installation on existing wiring.

J. Current Transformers.

1. AC current transformers shall be UL/CSA recognized and shall be completely encased (except for terminals) in approved plastic material.
2. Transformers shall be available in various current ratios and shall be selected for $\pm 1\%$ accuracy at 5 A full-scale output.
3. Use fixed-core transformers for new wiring installation and split-core transformers for existing wiring installation.

K. Voltage Transmitters.

1. AC voltage transmitters shall be self-powered single-loop (two-wire) type, 4–20 mA output with zero and span adjustment.
2. Adjustable full-scale unit ranges shall be 100–130 Vac, 200–250 Vac, 250–330 Vac, and 400–600 Vac. Unit accuracy shall be $\pm 1\%$ full-scale at 500 ohm maximum burden.
3. Transmitters shall meet or exceed ANSI/ISA S50.1 requirements and shall be UL/CSA recognized at 600 Vac rating.

L. Voltage Transformers.

1. AC voltage transformers shall be UL/CSA recognized, 600 Vac rated, and shall have built-in fuse protection.
2. Transformers shall be suitable for ambient temperatures of 4°C–55°C (40°F–130°F) and shall provide $\pm 0.5\%$ accuracy at 24 Vac and 5 VA load.
3. Windings (except for terminals) shall be completely enclosed with metal or plastic.

M. Power Monitors.

1. Selectable rate pulse output for kWh reading, 4–20 mA output for kW reading, N.O. alarm contact, and ability to operate with 5.0 amp current inputs or 0–0.33 volt inputs.
2. 1.0% full-scale true RMS power accuracy, +0.5 Hz, voltage input range 120–600 V, and auto range select.
3. Under voltage/phase monitor circuitry.
4. NEMA 1 enclosure.
5. Current transformers having a 0.5% FS accuracy, 600 VAC isolation voltage with 0–0.33 V output. If 0–5 A current transformers are provided, a three-phase disconnect/shorting switch assembly is required.

N. Current Switches.

1. Current-operated switches shall be self-powered, solid-state with adjustable trip current. Select switches to match application current and DDC system output requirements.

O. Pressure Transducers.

1. Transducers shall have linear output signal and field-adjustable zero and span.
2. Transducer sensing elements shall withstand continuous operating conditions of positive or negative pressure 50% greater than calibrated span without damage.
3. Water pressure transducer diaphragm shall be stainless steel with minimum proof pressure of 1000 kPa (150 psi). Transducer shall have 4–20 mA output, suitable mounting provisions, and block and bleed valves.
4. Water differential pressure transducer diaphragm shall be stainless steel with minimum proof pressure of 1000 kPa (150 psi). Over-range limit (differential pressure) and maximum static pressure shall be 2000 kPa (300 psi.) Transducer shall have 4–20 mA output, suitable mounting provisions, and 5-valve manifold.
5. manifold.

P. Differential Pressure Switches. Differential pressure switches (air or water service) shall be UL listed, SPDT snap-acting, pilot duty rated (125 VA minimum) and shall have scale range and differential suitable for intended application and NEMA 1 enclosure unless otherwise specified.

Q. Pressure-Electric (PE) Switches.

1. Shall be metal or neoprene diaphragm actuated, operating pressure rated for 0–175 kPa (0–25 psig), with calibrated scale minimum setpoint range of 14–125 kPa (2–18 psig) minimum, UL listed.
2. Provide one- or two-stage switch action (SPDT, DPST, or DPDT) as required by application. Electrically rated for pilot duty service (125 VA minimum) and /or for motor control.
3. Switches shall be open type (panel-mounted) or enclosed type for remote installation. Enclosed type shall be NEMA 1 unless otherwise specified.

4. Each pneumatic signal line to PE switches shall have permanent indicating gauge.
- R. Differential Pressure Transmitter - Air Media:
1. Design Standard Manufacturers:
 - a. Setra.
 - b. Other Substitutions are permitted.
 2. Range as required for application. Accuracy not less than plus/minus 0.25 percent full scale. Output signal 4 to 20 mA. Transmitter shall have 1/4 inch barbed pressure connections and separate zero and span adjustment knobs.
 3. Velocity Pressure For Terminal Units: 0 to 1.0 inches w.c.
 4. Velocity Pressure For Air Flow Measuring Stations: Refer to Manufacturer's literature for range.
 5. Space Differential Pressure: plus/minus 0.5 inches w.c.
 6. Duct Static Pressure: Bidirectional at plus/minus 5.0 inches w.c.
 7. Discharge Static Pressure: Bidirectional at 150 percent of duct classification.
 8. Relief Static Pressure: plus/minus 2.0 inches w.c.
 9. Filter Monitoring: 0 to 2.5 inches w.c.
- S. Occupancy Sensors. Occupancy sensors shall utilize Passive Infrared (PIR) and/or Microphonic Passive technology to detect the presence of people within a room. Sensors shall be mounted as indicated on the approved drawings. The sensor output shall be accessible by any lighting and/or HVAC controller in the system. Occupancy sensors shall be capable of being powered from the lighting or HVAC control panel, as shown on the drawings. Occupancy sensor delay shall be software adjustable through the user interface and shall not require manual adjustment at the sensor.
- T. HVAC Air Flow Stations: Provide airflow/temperature measurement devices (ATMD) where indicated on the plans. Fan inlet measurement devices shall not be substituted for duct or plenum measurement devices indicated on the plans.
1. Manufacturers: Subject to compliance with requirements, provide products by one of the following or an approved equal:
 - a. Ebtron (GTA-116P + Gold or HTA-104PE series).
 - b. Sierra
 - c. Kurtz
 1. Each ATMD shall consist of one or more sensor probes and a single, remotely mounted, microprocessor-based transmitter capable of independently processing up to 16 independently wired sensor assemblies.

2. Each sensor assembly shall contain two individually wired, hermetically sealed bead-in-glass thermistors.
3. Each transmitter shall have a 16-character alpha-numeric display capable of displaying airflow, temperature, system status, configuration settings and diagnostics.
4. Duct Mounted Probes and Transmitter
 - a. Each sensor assembly shall independently determine velocity and temperature at each measurement point.
 - b. Airflow accuracy shall be $\pm 2\%$ of reading over the entire operating airflow range.
 - c. Devices whose accuracy is the combined accuracy of the transmitter and sensor probes must demonstrate that the total accuracy meets the performance requirements of this specification throughout the measurement range.
 - d. Each sensor probe shall have an integral, U.L. listed, plenum rated cable and terminal plug for connection to the remotely mounted transmitter. All terminal plug interconnecting pins shall be gold plated.
 - e. The operating airflow range shall be 0 to 5,000 FPM unless otherwise indicated on the plans.
5. The transmitter shall be provided with a Bluetooth low energy interface card capable of transmitting all transmitter setup parameters, diagnostics, average airflow and temperature of the device and the airflow and temperature of each sensor node. Software capable of capturing and displaying this transmission will be available via download to Android or iOS phone or tablet. The software shall allow for setup parameters, airflow, temperature and diagnostic data to be saved on the phone or be emailed.
6. The transmitter shall be capable of communicating with other devices using all of the following interface options:
 - a. Linear analog output signals for airflow and temperature: Field selectable, fuse protected and isolated, 0-10VDC/4-20mA (4-wire)
 - b. RS-485: Field selectable BACnet-ARCNET, BACnet-MS/TP, Modbus-RTU.
7. Probe
 - a. Probe Performance Requirements: The sensor accuracy for airflow shall be at least $\pm 2\%$ of reading over the sensor probe operating ranges. The installed total accuracy for airflow shall be better than $\pm 3\%$ of reading over the sensor probe operating ranges when installed in accordance with manufacturers' guidelines. The sensor accuracy for temperature shall be better than $\pm 0.15^\circ \text{ F}$ over the entire operating range.
 - b. Probe Sensor Density: The number of independent sensing points shall be as indicated below.

Area (ft ²)	Area (m ²)	Sensors
<= 1	<= 0.093	2
>1 to <4	>0.093 to < 0.372	4
4 to <8	0.372 to < 0.743	6
8 to <12	0.743 to < 1.115	8
12 to <16	1.115 to < 1.486	12
>=16	>= 1.486	16

- c. Provide a 3-year manufacturer's warranty.

2.9 LOCAL CONTROL PANELS.

- A. All indoor control cabinets shall be fully enclosed NEMA 1 construction with (hinged door) key-lock latch and removable subpanels. A single key shall be common to all field panels and subpanels.
- B. Interconnections between internal and face-mounted devices shall be prewired with color-coded stranded conductors neatly installed in plastic troughs and/or tie-wrapped. Terminals for field connections shall be UL listed for 600 volt service, individually identified per control/ interlock drawings, with adequate clearance for field wiring. Control terminations for field connection shall be individually identified per control drawings.
- C. arance for field wiring. Control terminations for field connection shall be individually identified per control drawings.
- D. Provide ON/OFF power switch with overcurrent protection for control power sources to each local panel.

2.10 WIRING AND RACEWAYS

- A. Wire: Single conductor control wiring above 24 V.
 - 1. Wire Size: Minimum 14 AWG.
 - 2. Conductors: 7/24 soft annealed copper strand with 2- to 2.5-inch lay.
 - 3. Conductor Insulation: 600 V, Type THWN or Type THHN, and 90 deg C in accordance with UL 83.
 - 4. Conductor Insulation Colors: Black (hot), white (neutral), and green (ground).
 - 5. Furnish on spools.
- B. Single, Twisted-Shielded, Instrumentation Cable above 24 V:
 - 1. Wire Size: Minimum 18 AWG.
 - 2. Conductors: Twisted, 7/24 soft annealed copper strand with a 2- to 2.5-inch lay.
 - 3. Conductor Insulation: Type THHN/THWN or Type TFN rating.
 - 4. Conductor Insulation Colors:
 - a. Twisted Pair: Black and white.
 - b. Twisted Triad: Black, red, and white.

5. Shielding: 100 percent type, 0.35/0.5-mil aluminum/Mylar tape, helically applied with 25 percent overlap, and aluminum side in with tinned copper drain wire.
6. Outer Jacket Insulation: 600 V, 90 deg C rating, and Type TC cable.
7. Furnish on spools.

C. Single, Twisted-Shielded, Instrumentation Cable 24 V and Less:

1. Wire Size: Minimum 18 AWG.
2. Conductors: Twisted, 7/24 soft annealed copper stranding with a 2- to 2.5-inch lay.
3. Conductor Insulation: Nominal 15-mil thickness, constructed from flame-retardant PVC.
4. Conductor Insulation Colors:
 - a. Twisted Pair: Black and white.
 - b. Twisted Triad: Black, red, and white.
5. Shielding: 100 percent type, 1.35-mil aluminum/polymer tape, helically applied with 25 percent overlap, and aluminum side in with tinned copper drain wire.
6. Outer Jacket Insulation: 300 V, 105 deg C rating, and Type PLTC cable.
7. Furnish on spools.

D. General. Provide copper wiring, plenum cable, and raceways as specified in applicable sections of Division 26.

E. Insulated wire shall use copper conductors and shall be UL listed for 90°C (200°F) minimum service.

F. Low voltage wiring above accessible ceilings shall be plenum rated, open run, utilizing bridal rings every 3 feet.

2.11 FIBER OPTIC CABLE SYSTEM

- A. Optical Cable. Optical cables shall be duplex 900 mm tight-buffer construction designed for intra-building environments. Sheath shall be UL listed OFNP in accordance with NEC Article 770. Optical fiber shall meet the requirements of FDDI, ANSI X3T9.5 PMD for 62.5/125mm.
- B. Connectors. Field terminate optical fibers with ST type connectors. Connectors shall have ceramic ferrules and metal bayonet latching bodies.

PART 3 - EXECUTION

3.1 EXAMINATION

- A. The project plans shall be thoroughly examined for control device and equipment locations. Any discrepancies, conflicts, or omissions shall be reported to the architect/engineer for resolution before rough-in work is started.
- B. The contractor shall inspect the site to verify that equipment may be installed as shown. Any discrepancies, conflicts, or omissions shall be reported to the engineer for resolution before rough-in work is started.

- C. The contractor shall examine the drawings and specifications for other parts of the work. If head room or space conditions appear inadequate—or if any discrepancies occur between the plans and the contractor's work and the plans and the work of others—the contractor shall report these discrepancies to the engineer and shall obtain written instructions for any changes necessary to accommodate the contractor's work with the work of others. Any changes in the work covered by this specification made necessary by the failure or neglect of the contractor to report such discrepancies shall be made by—and at the expense of—this contractor

3.2 PROTECTION

- A. The contractor shall protect all work and material from damage by his/her work or employees and shall be liable for all damage thus caused.
- B. The contractor shall be responsible for his/her work and equipment until finally inspected, tested, and accepted. The contractor shall protect any material that is not immediately installed. The contractor shall close all open ends of work with temporary covers or plugs during storage and construction to prevent entry of foreign objects

3.3 COORDINATION

- A. Site.
 - 1. Where the mechanical work will be installed in close proximity to, or will interfere with, work of other trades, the contractor shall assist in working out space conditions to make a satisfactory adjustment. If the contractor installs his/her work before coordinating with other trades, so as to cause any interference with work of other trades, the contractor shall make the necessary changes in his/her work to correct the condition without extra charge.
 - 2. Coordinate and schedule work with other work in the same area and with work dependent upon other work to facilitate mutual progress.
 - 3. e area and with work dependent upon other work to facilitate mutual progress.
- B. Test and Balance.
 - 1. The contractor shall furnish a single set of all tools necessary to interface to the control system for test and balance purposes.
 - 2. The contractor shall provide training in the use of these tools. This training will be planned for a minimum of 4 hours.
 - 3. In addition, the contractor shall provide a qualified technician to assist in the test and balance process, until the first 20 terminal units are balanced.
 - 4. The tools used during the test and balance process will be returned at the completion of the testing and balancing
- C. Life Safety.
 - 1. Duct smoke detectors required for air handler shutdown are provided under Division 28. Interlock smoke detectors to air handlers for shutdown as specified in Section 23 09 93.11 (Sequences of Operation).

2. Smoke dampers and actuators required for duct smoke isolation are provided under Division 15. Interlock smoke dampers to air handlers as specified in Section 23 09 93.11 (Sequences of Operation).
 3. Fire and smoke dampers and actuators required for fire-rated walls are provided under Division 23. Fire and smoke damper control is provided under Division 28.
- D. Coordination with controls specified in other sections or divisions. Other sections and/or divisions of this specification include controls and control devices that are to be part of or interfaced to the control system specified in this section. These controls shall be integrated into the system and coordinated by the contractor as follows:
1. All communication media and equipment shall be provided as specified in Section 23 09 23 Article 2.2 (Communication).
 2. Each supplier of a controls product is responsible for the configuration, programming, start up, and testing of that product to meet the sequences of operation described in Section 23 09 93.11
 3. The contractor shall coordinate and resolve any incompatibility issues that arise between control products provided under this section and those provided under other sections or divisions of this specification.
 4. The contractor is responsible for providing all controls described in the contract documents regardless of where within the contract documents these controls are described
 5. The contractor is responsible for the interface of control products provided by multiple suppliers regardless of where this interface is described within the contract documents.
- 3.4 GENERAL WORKMANSHIP
- A. Install equipment, piping, and wiring/raceway parallel to building lines (i.e. horizontal, vertical, and parallel to walls) wherever possible.
 - B. Provide sufficient slack and flexible connections to allow for vibration of piping and equipment.
 - C. Install equipment in readily accessible locations as defined by Chapter 1 Article 100 Part A of the National Electrical Code (NEC).
 - D. Verify integrity of all wiring to ensure continuity and freedom from shorts and grounds.
 - E. All equipment, installation, and wiring shall comply with industry specifications and standards for performance, reliability, and compatibility and be executed in strict adherence to local codes and standard practices.
- 3.5 FIELD QUALITY CONTROL
- A. All work, materials, and equipment shall comply with rules and regulations of applicable local, state, and federal codes and ordinances.

- B. Contractor shall continually monitor the field installation for code compliance and quality of workmanship.
- C. Contractor shall have work inspection by local and/or state authorities having jurisdiction over the work.

3.6 WIRING

- A. All control and interlock wiring shall comply with national and local electrical codes, and Division 26 of this specification. Where the requirements of this section differ from Division 26, the requirements of this section shall take precedence.
- B. All NEC Class 1 (line voltage) wiring shall be UL listed in approved raceway according to NEC and Division 26 requirements.
- C. All low-voltage wiring shall meet NEC Class 2 requirements. Low-voltage power circuits shall be subfused when required to meet Class 2 current limit.
- D. Where NEC Class 2 (current-limited) wires are in concealed and accessible locations, including ceiling return air plenums, approved cables not in raceway may be used provided that cables are UL listed for the intended application.
- E. All wiring in mechanical, electrical, or service rooms – or where subject to mechanical damage – shall be installed in raceway at levels below 3 m (10ft).
- F. Do not install Class 2 wiring in raceways containing Class 1 wiring. Boxes and panels containing high-voltage wiring and equipment may not be used for low-voltage wiring except for the purpose of interfacing the two (e.g. relays and transformers).
- G. Do not install wiring in raceway containing tubing.
- H. Where Class 2 wiring is run exposed, wiring is to be run parallel along a surface or perpendicular to it and neatly tied at 3 m (10 ft) intervals.
- I. Where plenum cables are used without raceway, they shall be supported from or anchored to structural members. Cables shall not be supported by or anchored to ductwork, electrical raceways, piping, or ceiling suspension systems.
- J. All wire-to-device connections shall be made at a terminal block or terminal strip. All wire-to-wire connections shall be at a terminal block.
- K. All wiring within enclosures shall be neatly bundled and anchored to permit access and prevent restriction to devices and terminals.
- L. Maximum allowable voltage for control wiring shall be 120 V. If only higher voltages are available, the contractor shall provide step-down transformers.
- M. All wiring shall be installed as continuous lengths, with no splices permitted between termination points.
- N. Install plenum wiring in sleeves where it passes through walls and floors. Maintain fire rating at all penetrations.

- O. Size of raceway and size and type of wire shall be the responsibility of the contractor in keeping with the manufacturer's recommendations and NEC requirements, except as noted elsewhere.
- P. Include one pull string in each raceway 2.5 cm (1 in.) or larger.
- Q. Use color-coded conductors throughout with conductors of different colors.
- R. Control and status relays are to be located in designated enclosures only. These enclosures include packaged equipment control panel enclosures unless they also contain Class 1 starters.
- S. Conceal all raceways except within mechanical, electrical, or service rooms. Install raceway to maintain a minimum clearance of 15 cm (6 in.) from high-temperature equipment (e.g. steam pipes or flues).
- T. Secure raceways with raceway clamps fastened to the structure and spaced according to code requirements. Raceways and pull boxes may not be hung on flexible duct strap or tie rods. Raceways may not be run on or attached to ductwork.
- U. Adhere to this specification's Division 26 requirements where raceway crosses building expansion joints.
- V. Install insulated bushings on all raceway ends and openings to enclosures. Seal top end of vertical raceways.
- W. The contractor shall terminate all control and/or interlock wiring and shall maintain updated (as-built) wiring diagrams with terminations identified at the job site.
- X. Flexible metal raceways and liquid-tight flexible metal raceways shall not exceed 1 m (3 ft) in length and shall be supported at each end. Flexible metal raceway less than ½ in. electrical trade size shall not be used. In areas exposed to moisture, including chiller and boiler rooms, liquid-tight, flexible metal raceways shall be used.
- Y. Raceway must be rigidly installed, adequately supported, properly reamed at both ends, and left clean and free of obstructions. Raceway sections shall be joined with couplings (according to code). Terminations must be made with fittings at boxes and ends not terminating in boxes shall have bushings installed.

3.7 COMMUNICATION WIRING

- A. The contractor shall adhere to the items listed in the Wiring" article in Part 3 of the specification.
- B. All cabling shall be installed in a neat and workmanlike manner. Follow manufacturer's installation recommendations for all communication cabling.
- C. Do not install communication wiring in raceways and enclosures containing Class 1 or other Class 2 wiring.
- D. Maximum pulling, tension, and bend radius for the cable installation, as specified by the cable manufacturer, shall not be exceeded during installation.

- E. Contractor shall verify the integrity of the entire network following cable installation. Use appropriate test measures for each particular cable.
- F. When a cable enters or exits a building, a lightning arrestor must be installed between the lines and ground. The lightning arrestor shall be installed according to manufacturer's instructions.
- G. All runs of communication wiring shall be unspliced length when that length is commercially available.
- H. All communication wiring shall be labeled to indicate origination and destination data.
- I. Grounding of coaxial cable shall be in accordance with NEC regulations article on "Communications Circuits, Cable, and Protector Grounding."
- J. BACnet Arcnet or MS/TP communications wiring shall be installed in accordance with ASHRAE/ANSI Standard 135. This includes but is not limited to:

1. Arcnet

- a. The network shall use shielded, twisted-pair cable with characteristic impedance between 100 nominal. Distributed capacitance between conductors shall be less than 12.5 pF per foot (41 pF per meter.)
- b. The maximum length of an Arcnet segment is 610 meters (2000 ft) with AWG 22 cable.
- c. The maximum number of nodes per segment shall be 32, as specified in the EIA 485 standard. Additional nodes may be accommodated by the use of repeaters.
- d. An Arcnet network shall have no T connections.

2. MS/TP

- a. The network shall use shielded, twisted-pair cable with characteristic impedance between 100 and 120 ohms. Distributed capacitance between conductors shall be less than 100 pF per meter (30 pF per foot.)
- b. The maximum length of an MS/TP segment is 1200 meters (4000 ft) with AWG 18 cable. The use of greater distances and/or different wire gauges shall comply with the electrical specifications of EIA-485
- c. The maximum number of nodes per segment shall be 32, as specified in the EIA 485 standard. Additional nodes may be accommodated by the use of repeaters.
- d. An MS/TP EIA-485 network shall have no T connections.

3.8 FIBER OPTIC CABLE

- A. Maximum pulling tensions as specified by the cable manufacturer shall not be exceeded during installation. Post-installation residual cable tension shall be within cable manufacturer's specifications.
- B. All cabling and associated components shall be installed in accordance with manufacturers' instructions. Minimum cable and unjacketed fiber bend radii, as specified by cable manufacturer, shall be maintained.

3.9 INSTALLATION OF SENSORS

- A. Install sensors in accordance with the manufacturer's recommendations.
- B. Mount sensors rigidly and adequately for environment within which the sensor operates.
- C. Room temperature sensors shall be installed on concealed junction boxes properly supported by wall framing.
- D. All wires attached to sensors shall be sealed in their raceways or in the wall to stop air transmitted from other areas from affecting sensor readings.
- E. Sensors used in mixing plenums and hot and cold decks shall be of the averaging type. Averaging sensors shall be installed in a serpentine manner vertically across the duct. Each bend shall be supported with a capillary clip.
- F. Low-limit sensors used in mixing plenums shall be installed in a serpentine manner horizontally across duct. Each bend shall be supported with a capillary clip. Provide 3 m (1 ft) of sensing element for each 1 m² (1 ft²) of coil area.
- G. All pipe-mounted temperature sensors shall be installed in wells. Install liquid temperature sensors with heat-conducting fluid in thermal wells.
- H. Install outdoor air temperature sensors on north wall, complete with sun shield at designated location.
- I. Differential Air Static Pressure.
 - 1. Supply Duct Static Pressure. Pipe the high-pressure tap to the duct using a pitot tube. Pipe the low-pressure port to a tee in the high-pressure tap tubing of the corresponding building static pressure sensor (if applicable) or to the location of the duct high-pressure tap and leave open to the plenum.
 - 2. Return Duct Static Pressure. Pipe high-pressure tap to duct using a pitot tube. Pipe the low-pressure port to a tee in the low-pressure tap tubing of the corresponding building static pressure sensor.
 - 3. Building Static Pressure. Pipe the low-pressure port of the pressure sensor to the static pressure port located on the outside of the building through a high-volume accumulator. Pipe the high-pressure port to a location behind a thermostat cover.

4. The piping to the pressure ports on all pressure transducers shall contain a capped test port located adjacent to the transducer.
 5. All pressure transducers, other than those controlling VAV boxes, shall be located in field device panels, not on the equipment monitored or on ductwork. Mount transducers in a location accessible for service without use of ladders or special equipment.
 6. All air and water differential pressure sensors shall have gauge tees mounted adjacent to the taps. Water gauges shall also have shut-off valves installed before the tee.
- J. Smoke detectors, freezestats, high-pressure cut-offs, and other safety switches shall be hard-wired to de-energize equipment as described in the sequence of operation. Switches shall require manual reset. Provide contacts that allow DDC software to monitor safety switch status.
- K. Install humidity sensors for duct mounted humidifiers at least 3 m (10 ft) downstream of the humidifier. Do not install filters between the humidifier and the sensor.
- 3.10 ACTUATORS
- A. General. Mount and link control damper actuators according to manufacturer's instructions.
1. To compress seals when spring-return actuators are used on normally closed dampers, power actuator to approximately 5° open position, manually close the damper, and then tighten the linkage.
 2. Check operation of damper/actuator combination to confirm that actuator modulates damper smoothly throughout stroke to both open and closed positions.
 3. Provide all mounting hardware and linkages for actuator installation.
- B. Electric/ Electronic
1. Dampers: Actuators shall be direct mounted on damper shaft or jackshaft unless shown as a linkage installation. For low-leakage dampers with seals, the actuator shall be mounted with a minimum 5° travel available for tightening the damper seal. Actuators shall be mounted following manufacturer's recommendations.
 2. Valves: Actuators shall be connected to valves with adapters approved by the actuator manufacturer. Actuators and adapters shall be mounted following the actuator manufacturer's recommendations.

3.11 WARNING LABELS

- A. Permanent warning labels shall be affixed to all equipment that can be automatically started by the control system.
1. Labels shall use white lettering (12-point type or larger) on a red background.
 2. Warning labels shall read as follows.
 - a. C A U T I O N: This equipment is operating under automatic control and may start or stop at any time without warning. Switch disconnect to "Off" position before servicing.

- B. Permanent warning labels shall be affixed to all motor starters and control panels that are connected to multiple power sources utilizing separate disconnects.
 - 1. Labels shall use white lettering (12-point type or larger) on a red background.
 - 2. Warning labels shall read as follows.
 - a. C A U T I O N: This equipment is fed from more than one power source with separate disconnects. Disconnect all power sources before servicing.

3.12 IDENTIFICATION OF HARDWARE AND WIRING

- A. All wiring and cabling, including that within factory-fabricated panels, shall be labeled at each end within 5 cm (2 in.) of termination with control system address or termination number.
- B. All pneumatic tubing shall be labeled at each end within 5 cm (2 in.) of termination with a descriptive identifier.
- C. Permanently label or code each point of field terminal strips to show the instrument or item served.
- D. Identify control panels with minimum 1 cm (½ in.) letters on laminated plastic nameplates.
- E. Identify all other control components with permanent labels. All plug-in components shall be labeled such that removal of the component does not remove the label.
- F. Identify room sensors related to terminal boxes or valves with nameplates.
- G. Manufacturers' nameplates and UL or CSA labels shall be visible and legible after equipment is installed.
- H. Identifiers shall match record documents.

3.13 CONTROLLERS

- A. Provide a separate controller for each AHU or other HVAC system. A DDC controller may control more than one system provided that all points associated with the system are assigned to the same DDC controller. Points used for control loop reset, such as outside air or space temperature, are exempt from this requirement.
- B. Building Controllers and Custom Application Controllers shall be selected to provide the required I/O point capacity required to monitor all of the hardware points listed in Section 230993.11 "Sequence of Operations for HVAC DDC".

3.14 PROGRAMMING

- A. Provide sufficient internal memory for the specified sequences of operation and trend logging
- B. Point Naming. Name points as shown on the equipment points list provided with each sequence of operation. If character limitations or space restrictions make it advisable to shorten the name, the abbreviations may be used. Where multiple points with the same name reside in the same controller, each point name may be customized with its associated Program Object number. For example, "Zone Temp 1" for Zone 1, "Zone Temp 2" for Zone 2.

C. Software Programming.

1. Provide programming for the system and adhere to the sequences of operation provided. All other system programming necessary for the operation of the system, but not specified in this document, also shall be provided by the contractor. Imbed into the control program sufficient comment statements to clearly describe each section of the program. The comment statements shall reflect the language used in the sequences of operation. Use the appropriate technique based on the following programming types:
2. Programming types:
 - a. Text-based:
 - 1) Must provide actions for all possible situations
 - 2) Must be modular and structured
 - 3) Must be commented
 - b. Graphic-based:
 - 1) Must provide actions for all possible situations
 - 2) Must be documented
 - c. Parameter-based:
 - 1) Must provide actions for all possible situations
 - 2) Must be documented.

D. Operator Interface.

1. Standard Graphics. Provide graphics for all mechanical systems and floor plans of the building. This includes each boiler, air handler, and all terminal equipment. Point information on the graphic displays shall dynamically update. Show on each graphic all input and output points for the system. Also show relevant calculated points such as setpoints. As a minimum, show on each equipment graphic the input and output points and relevant calculated point.
2. The contractor shall provide all the labor necessary to install, initialize, start up, and troubleshoot all operator interface software and its functions as described in this section. This includes any operating system software, the operator interface database, and any third-party software installation and integration required for successful operation of the operator interface.

3.15 CONTROL SYSTEM CHECKOUT AND TESTING

- A. Startup Testing. All testing listed in this article shall be performed by the contractor and shall make up part of the necessary verification of an operating control system. This testing shall be completed before the owner's representative is notified of the system demonstration
1. The contractor shall furnish all labor and test apparatus required to calibrate and prepare for service of all instruments, controls, and accessory equipment furnished under this specification.
 2. Verify that all control wiring is properly connected and free of all shorts and ground faults. Verify that terminations are tight.
 3. Enable the control systems and verify calibration of all input devices individually. Perform calibration procedures according to manufacturers' recommendations.

4. Verify that all binary output devices (relays, solenoid valves, two-position actuators and control valves, magnetic starters, etc.) operate properly and that the normal positions are correct.
5. Verify that all analog output devices (I/Ps, actuators, etc.) are functional, that start and span are correct, and that direction and normal positions are correct. The contractor shall check all control valves and automatic dampers to ensure proper action and closure. The contractor shall make any necessary adjustments to valve stem and damper blade travel.
6. Verify that the system operation adheres to the sequences of operation. Simulate and observe all modes of operation by overriding and varying inputs and schedules. Tune all DDC loops.

7. Alarms and Interlocks:

- a. Check each alarm separately by including an appropriate signal at a value that will trip the alarm.
- b. Interlocks shall be tripped using field contacts to check the logic, as well as to ensure that the fail-safe condition for all actuators is in the proper direction.
- c. Interlock actions shall be tested by simulating alarm conditions to check the initiating value of the variable and interlock action.

3.16 CONTROL SYSTEM DEMONSTRATION AND ACCEPTANCE

A. Demonstration.

1. Prior to acceptance, the control system shall undergo a series of performance tests to verify operation and compliance with this specification. These tests shall occur after the Contractor has completed the installation, started up the system, and performed his/her own tests.
2. The tests described in this section are to be performed in addition to the tests that the contractor performs as a necessary part of the installation, start-up, and debugging process and as specified in the "Control System Checkout and Testing" article in Part 3 of this specification. The engineer will be present to observe and review these tests. The engineer shall be notified at least 10 days in advance of the start of the testing procedures.
3. d Testing" article in Part 3 of this specification. The engineer will be present to observe and review these tests. The engineer shall be notified at least 10 days in advance of the start of the testing procedures.
4. The demonstration process shall follow that approved in Part 1, "Submittals." The approved checklists and forms shall be completed for all systems as part of the demonstration.
5. The contractor shall provide at least two persons equipped with two-way communication and shall demonstrate actual field operation of each control and sensing point for all modes of operation including day, night, occupied, unoccupied, fire/smoke alarm, seasonal changeover, and power failure modes. The purpose is to demonstrate the calibration, response, and action of every point and system. Any test equipment required to prove the proper operation shall be provided by and operated by the contractor.
6. alibration, response, and action of every point and system. Any test equipment required to prove the proper operation shall be provided by and operated by the contractor.
7. As each control input and output is checked, a log shall be completed showing the date, technician's initials, and any corrective action taken or needed.
8. Demonstrate compliance with Part 1, "System Performance."
9. Demonstrate compliance with sequences of operation through all modes of operation.
10. Demonstrate complete operation of operator interface.

11. Additionally, the following items shall be demonstrated:
 - a. DDC loop response. The contractor shall supply trend data output in a graphical form showing the step response of each DDC loop. The test shall show the loop's response to a change in set point, which represents a change of actuator position of at least 25% of its full range. The sampling rate of the trend shall be from 10 seconds to 3 minutes, depending on the speed of the loop. The trend data shall show for each sample the set point, actuator position, and controlled variable values. Any loop that yields unreasonably under-damped or over-damped control shall require further tuning by the Contractor.
 - b. Demand limiting. The contractor shall supply a trend data output showing the action of the demand limiting algorithm. The data shall document the action on a minute-by-minute basis over at least a 30-minute period. Included in the trend shall be building kW, demand limiting set point, and the status of sheddable equipment outputs.
 - c. action on a minute-by-minute basis over at least a 30-minute period. Included in the trend shall be building kW, demand limiting set point, and the status of sheddable equipment outputs.
 - d. Optimum start/stop. The contractor shall supply a trend data output showing the capability of the algorithm. The change-of-value or change-of-state trends shall include the output status of all optimally started and stopped equipment, as well as temperature sensor inputs of affected areas.
 - e. Interface to the building fire alarm system.
 - f. Operational logs for each system that indicate all set points, operating points, valve positions, mode, and equipment status shall be submitted to the architect/engineer. These logs shall cover three 48-hour periods and have a sample frequency of not more than 10 minutes. The logs shall be provided in both printed and disk formats.
12. Any tests that fail to demonstrate the operation of the system shall be repeated at a later date. The contractor shall be responsible for any necessary repairs or revisions to the hardware or software to successfully complete all tests
13. he hardware or software to successfully complete all tests

B. Acceptance.

1. All tests described in this specification shall have been performed to the satisfaction of both the engineer and owner prior to the acceptance of the control system as meeting the requirements of completion. Any tests that cannot be performed due to circumstances beyond the control of the contractor may be exempt from the completion requirements if stated as such in writing by the engineer. Such tests shall then be performed as part of the warranty.
2. The system shall not be accepted until all forms and checklists completed as part of the demonstration are submitted and approved as required in Part 1, "Submittals."

3.17 CLEANING

- A. The contractor shall clean up all debris resulting from his/her activities daily. The contractor shall remove all cartons, containers, crates, etc., under his/her control as soon as their contents have been removed. Waste shall be collected and placed in a designated location.
- B. At the completion of work in any area, the contractor shall clean all work, equipment, etc., keeping it free from dust, dirt, and debris, etc.
- C. At the completion of work, all equipment furnished under this section shall be checked for paint damage, and any factory-finished paint that has been damaged shall be repaired to match the adjacent areas. Any cabinet or enclosure that has been deformed shall be replaced with new material and repainted to match the adjacent areas.

3.18 TRAINING

- A. Provide training for a designated staff of Owner's representatives. Training shall be provided via self-paced training, web-based or computer-based training, classroom training, or a combination of training methods.
- B. Training shall enable students to accomplish the following objectives.
 - 1. Day-to-day Operators:
 - a. Proficiently operate the system
 - b. Understand control system architecture and configuration
 - c. Understand DDC system components
 - d. Understand system operation, including DDC system control and optimizing routines (algorithms)
 - e. Operate the workstation and peripherals
 - f. Log on and off the system
 - g. Access graphics, point reports, and logs
 - h. Adjust and change system set points, time schedules, and holiday schedules
 - i. Recognize malfunctions of the system by observation of the printed copy and graphical visual signals
 - j. Understand system drawings and Operation and Maintenance manual
 - k. Understand the job layout and location of control components
 - l. Access data from DDC controllers and ASCs
 - m. Operate portable operator's terminals
 - 2. Advanced Operators:

- a. Make and change graphics on the workstation
 - b. Create, delete, and modify alarms, including annunciation and routing of these
 - c. Create, delete, and modify point trend logs and graph or print these both on an ad-hoc basis and at user-definable time intervals
 - d. Create, delete, and modify reports
 - e. Add, remove, and modify system's physical points
 - f. Create, modify, and delete programming
 - g. Add panels when required
 - h. Add operator interface stations
 - i. Create, delete, and modify system displays, both graphical and others
 - j. Perform DDC system field checkout procedures
 - k. Perform DDC controller unit operation and maintenance procedures
 - l. Perform workstation and peripheral operation and maintenance procedures
 - m. Perform DDC system diagnostic procedures
 - n. Configure hardware including PC boards, switches, communication, and I/O points
 - o. Maintain, calibrate, troubleshoot, diagnose, and repair hardware
 - p. Adjust, calibrate, and replace system components
3. System Managers/Administrators:
- a. Maintain software and prepare backups
 - b. Interface with job-specific, third-party operator software
 - c. Add new users and understand password security procedures
- C. Organize the training into sessions or modules for the three levels of operators listed above. (Day-to-Day Operators, Advanced Operators, System Managers and Administrators). Students will receive one or more of the training packages, depending on knowledge level required.
- D. The instructor(s) shall be factory-trained and experienced in presenting this material.
- E. Classroom training shall be done using a network of working controllers representative of installed hardware.
- 3.19 CONTROL DAMPER INSTALLATION
- A. Damper submittals shall be coordinated for type, quantity, and size to ensure compatibility with sheet metal design.

- B. Duct openings shall be free of any obstruction or irregularities that might interfere with blade or linkage rotation or actuator mounting. Duct openings shall measure $\frac{1}{4}$ in. larger than damper dimensions and shall be square, straight, and level.
- C. Individual damper sections, as well as entire multiple section assemblies, must be completely square and free from racking, twisting, or bending. Measure diagonally from upper corners to opposite lower corners of each damper section. Both dimensions must be within 0.3 cm (1/8 in.) of each other.
- D. .3 cm (1/8 in.) of each other.
- E. Follow the manufacturer's instructions for field installation of control dampers. Unless specifically designed for vertical blade application, dampers must be mounted with blade axis horizontal.
- F. Install extended shaft or jackshaft according to manufacturer's instructions. (Typically, a sticker on the damper face shows recommended extended shaft location. Attach shaft on labeled side of damper to that blade.)
- G. Damper blades, axles, and linkage must operate without binding. Before system operation, cycle damper after installation to ensure proper operation. On multiple section assemblies, all sections must open and close simultaneously.
- H. Provide a visible and accessible indication of damper position on the drive shaft end.
- I. Support ductwork in area of damper when required to prevent sagging due to damper weight.
- J. After installation of low-leakage dampers with seals, caulk between frame and duct or opening to prevent leakage around perimeter of damper.

3.20 DUCT SMOKE DETECTION

- A. This Contractor shall provide a dry-contact alarm output in the same room as the HVAC equipment to be controlled.

3.21 PACKAGED EQUIPMENT CONTROLS

- A. General. The electronic controls packaged with any equipment furnished under this contract shall communicate with the building direct digital control (DDC) system. The DDC system shall communicate with these controls to read the information and change the control setpoints as shown in the points list, sequences of operation, and control schematics. The information to be communicated between the DDC system and these controls shall be in the standard object format as defined in ANSI/ASHRAE Standard 135 (BACnet). Controllers shall communicate with other BACnet objects on the internetwork using the Read (Execute) Property service as defined in Clause 15.5 of Standard 135.
- B. t). Controllers shall communicate with other BACnet objects on the internetwork using the Read (Execute) Property service as defined in Clause 15.5 of Standard 135.
- C. Distributed Processing. The controller shall be capable of stand-alone operation and shall continue to provide control functions if the network connection is lost.

- D. I/O Capacity. The controller shall contain sufficient I/ O capacity to control the target system.
- E. The Controller shall have a physical connection for a laptop computer or a portable operator's tool.
- F. Environment. The hardware shall be suitable for the anticipated ambient conditions.
 - 1. Controllers used outdoors and/or in wet ambient conditions shall be mounted within waterproof enclosures and shall be rated for operation at -29°C to 60°C (-20°F to 140°F).
 - 2. Controllers used in conditioned space shall be mounted in dust-proof enclosures and shall be rated for operation at 0°C to 50°C (32°F to 120°F).
- G. Serviceability. Provide diagnostic LEDs for power, communication, and processor. All wiring connections shall be made to field removable, modular terminal strips or to a termination card connected by a ribbon cable.
- H. Memory. The Controller shall maintain all BIOS and programming information in the event of a power loss for at least 30 days.
- I. Power. Controller shall be able to operate at 90% to 110% of nominal voltage rating .
- J. Transformer. Power supply for the Controller must be rated at minimum of 125% of ASC power consumption and shall be fused or current limiting type.

3.22 START-UP AND CHECKOUT PROCEDURES

- A. Start up, check out, and test all hardware and software and verify communication between all components.
 - 1. Verify that all control wiring is properly connected and free of all shorts and ground faults. Verify that terminations are tight.
 - 2. Verify that all analog and binary input/output points read properly.
 - 3. Verify alarms and interlocks.
 - 4. Verify operation of the integrated system.

END OF SECTION 230923